



# Decentralized Federated Learning Over Edge Networks: a Coordination-Free Learning Substrate for Agentic AI

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**Lorenzo Valerio, PhD**

**CNR-IIT**

**[lorenzo.valerio@iit.cnr.it](mailto:lorenzo.valerio@iit.cnr.it)**

# What is agentic AI: Definition

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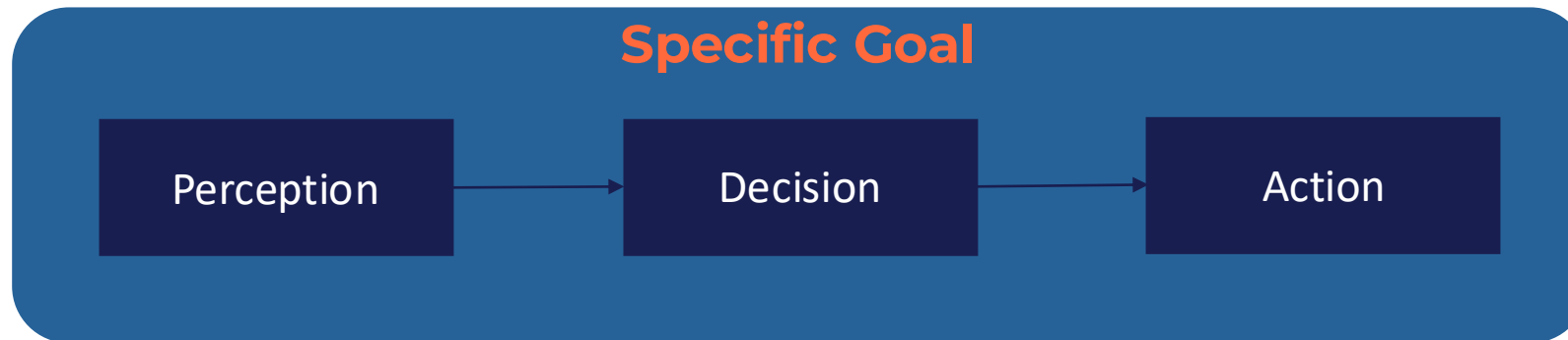
- Agentic AI is an **artificial intelligence system** that can accomplish a **specific goal** with **limited supervision**.
- It **consists** of **AI agents**
  - machine learning models that mimic human decision-making to solve problems in real time.
- In a **multiagent system**, each agent can perform a **specific subtask** required to reach the goal and their efforts are coordinated through AI orchestration



# Agentic AI: How do they do it?

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Agentic AI systems can **perceive**, **decide**, and **act** to accomplish goals with minimal human intervention.



Key shift vs. traditional AI: closed-loop autonomy

# Autonomous agents: characteristics

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- **Autonomy**: self-governing decision making
- **Reactivity**: timely response to environmental changes
- **Proactivity**: takes initiative to pursue goals
- **Goal-oriented behavior**: plan → execute → monitor → adapt
- **Social ability**: communicate, coordinate, negotiate



# Autonomous agents: architectural styles

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## **Reactive**

Direct perception → action, minimal state (fast)

## **Deliberative**

Internal state + planning to reach goals

## **Hybrid**

Layered reactive + deliberative control

# Elements of an Agentic AI as a multi-agent system

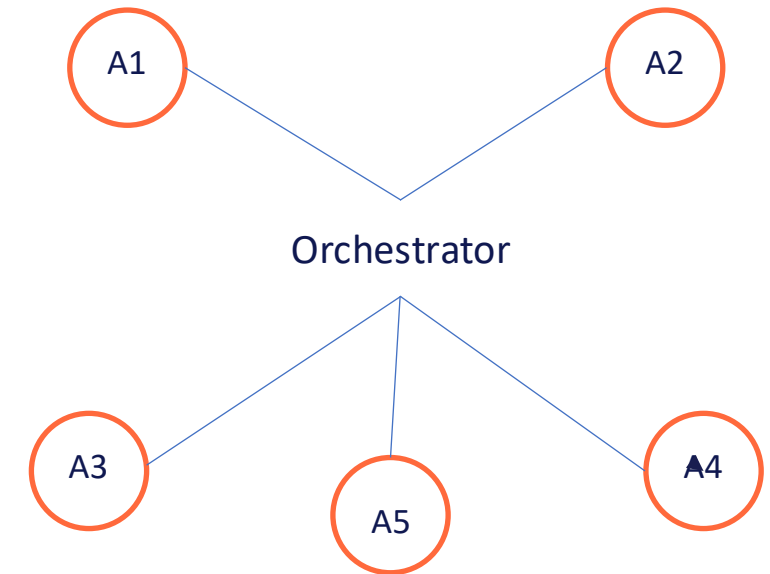
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**Coordination:** multiple agents work toward common or individual goals

**Communication & negotiation:** share information, allocate tasks, resolve conflicts

**Emergent behavior:** system-level patterns from local interactions

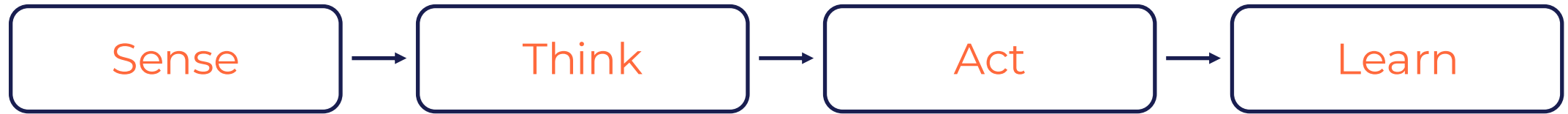
**Distributed AI:** decentralized control + local rules



# Moving Agentic AI @ the edge...

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Considering:



Limited **compute** capability

**Lack of coordination**



Intermittent **connectivity**

**Locality:** fragmented local views

**RQ:** How do agents share and improve their internal models without a central coordinator?





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# Decentralized federated learning (as a coordination free learning layer)



The **goal** of **DFL @ the edge** is to go...



from this

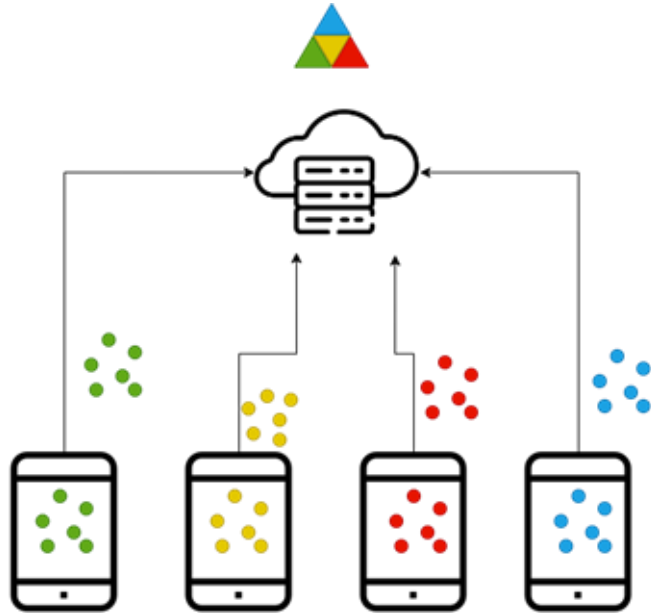


to this



# AI network architectures

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THE PAST



THE PRESENT

# Benefits of federated learning

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- **Privacy preservation**
- **Data security**
- **Collaboration without data sharing**
- Efficient data utilization
- Reduced communication costs
- Increased scalability



## Still, you need the central server to orchestrate the learning process

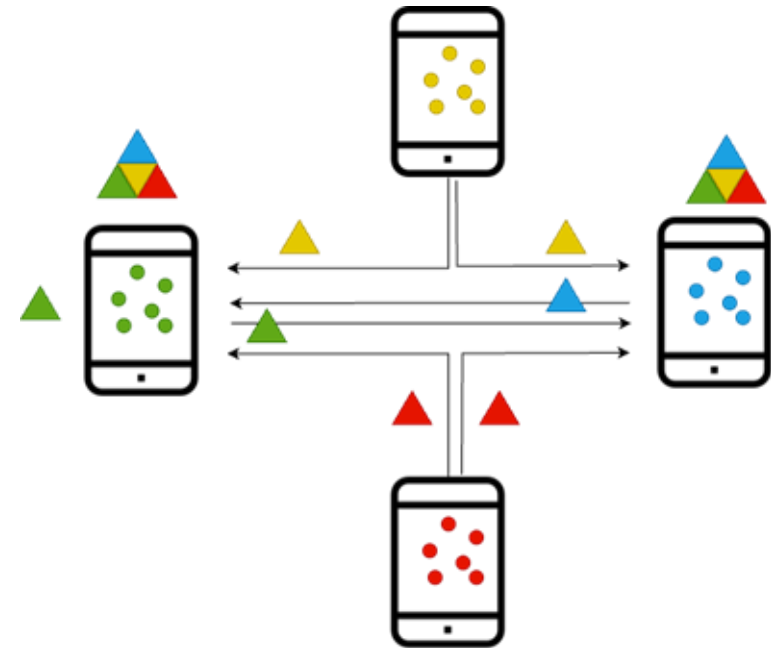
- Communication overhead
- Network dependency
- Centralized control and governance



# Fully decentralized learning

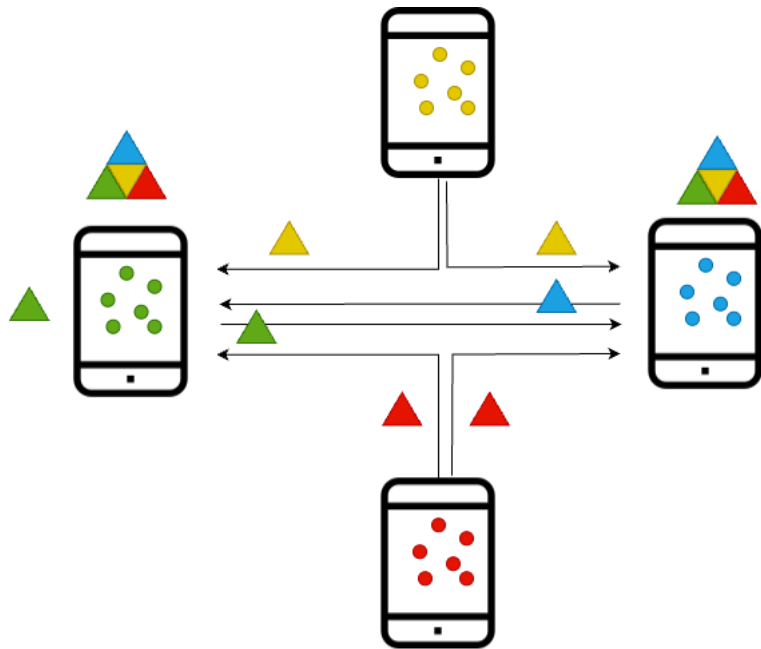
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Let's get rid of the central controller, then!



THE FUTURE

# Challenges of fully decentralized learning



- **Peer-to-Peer Communication** → how information flows becomes critical for learning, which is a by-product of the **graph topology** connecting nodes  
[Palmieri et al., 2024] [Palmieri et al., 2023]
- **Data localization** → data partitioned across devices, usually in a **non-IID** way, issues of small data  
[Ahmad et al., 2025]
- **Resilience of collaborative learning** → issues of **trust**, low-quality data, malicious nodes  
[Sabella et al., 2025]
- **No centralized control** → lack of **coordination**  
[Valerio et al., 2023] [Badie-Modiri et al., 2024]
- **On-device learning** → address the **resource constraints**  
[Valerio et al., 2022]
- **Local decision making** → device and model **heterogeneity**, local resources limited



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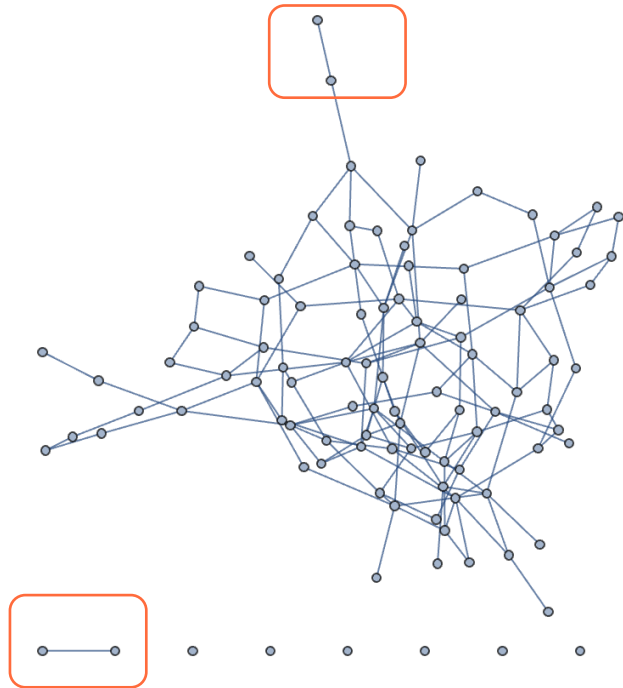
## Research direction #1:

What is the effect of different network topologies on the accuracy of decentralized learning?



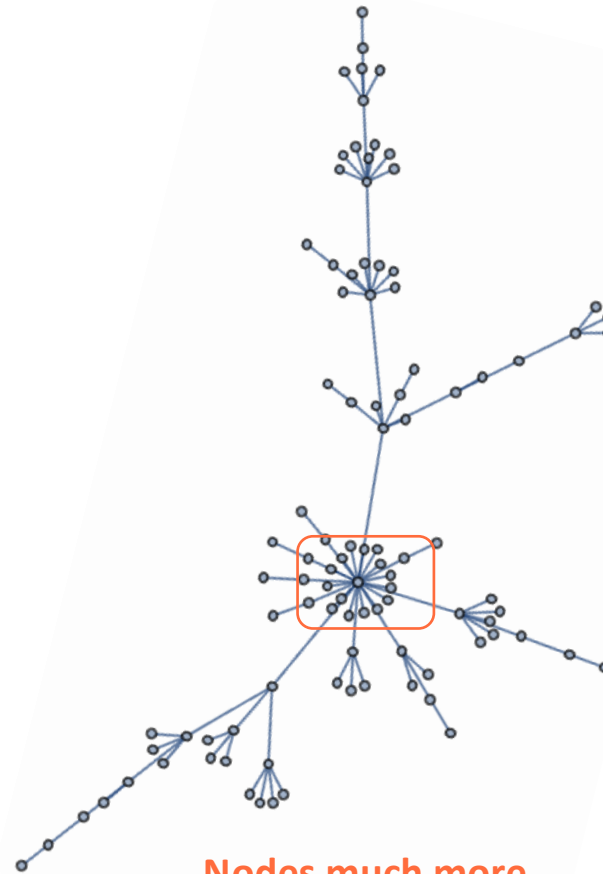
# Why it is a crucial problem

Poorly connected nodes



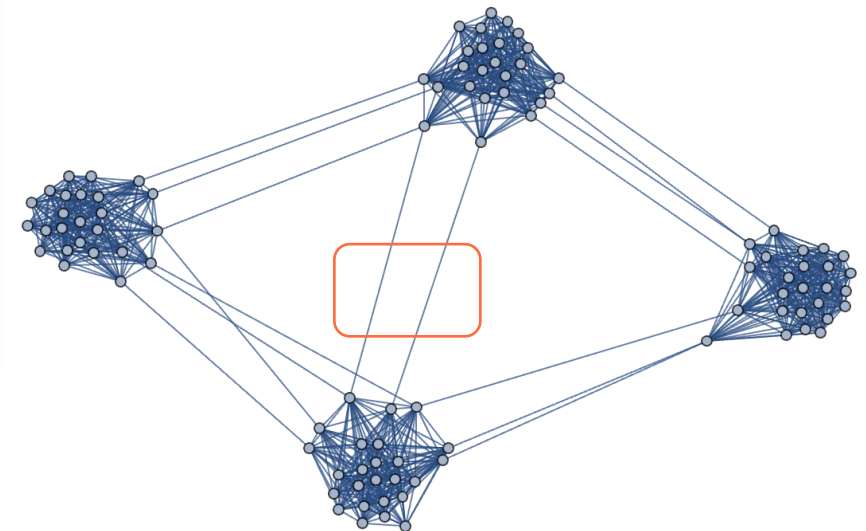
Erdős-Rényi graph

Barabási-Albert graph



Nodes much more  
"important" than others


Stochastic Block Model




Communities that are well  
connected inside and poorly  
connected outside

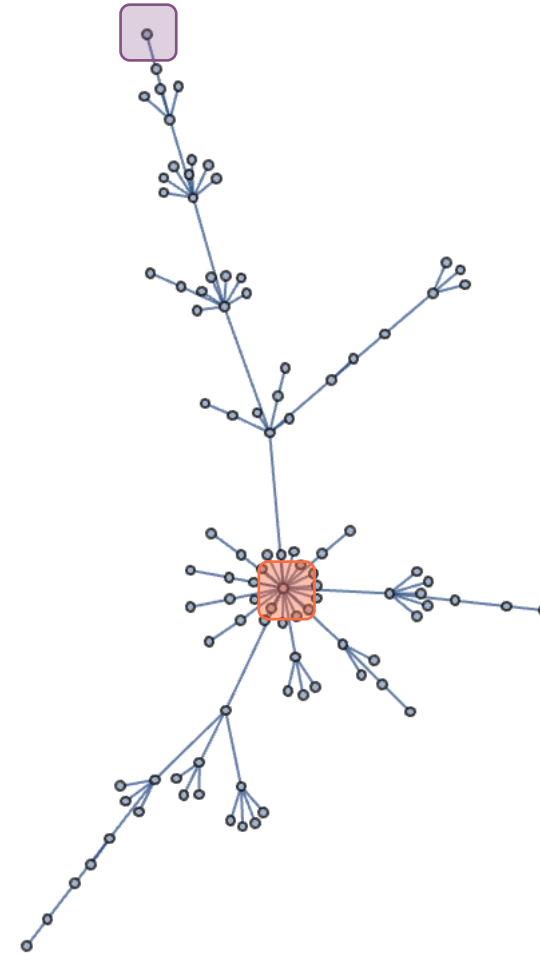
# Experiments

- Data allocation
  - 10 MNIST classes divided into **two groups**
  - G1



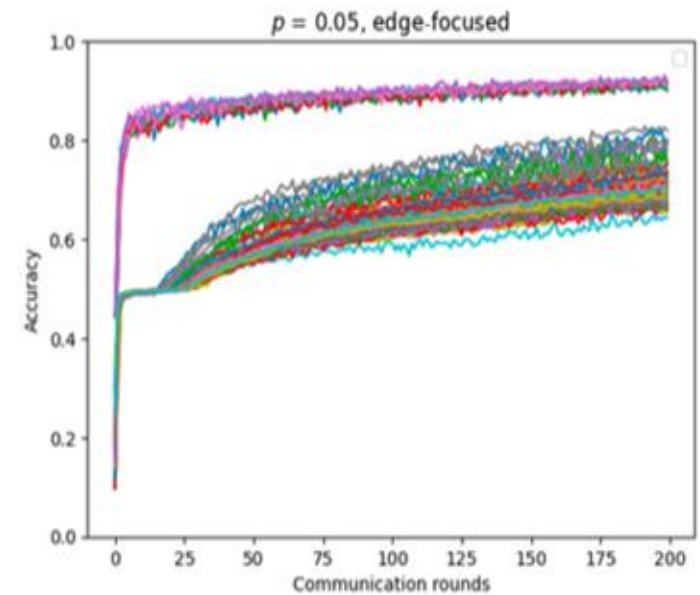
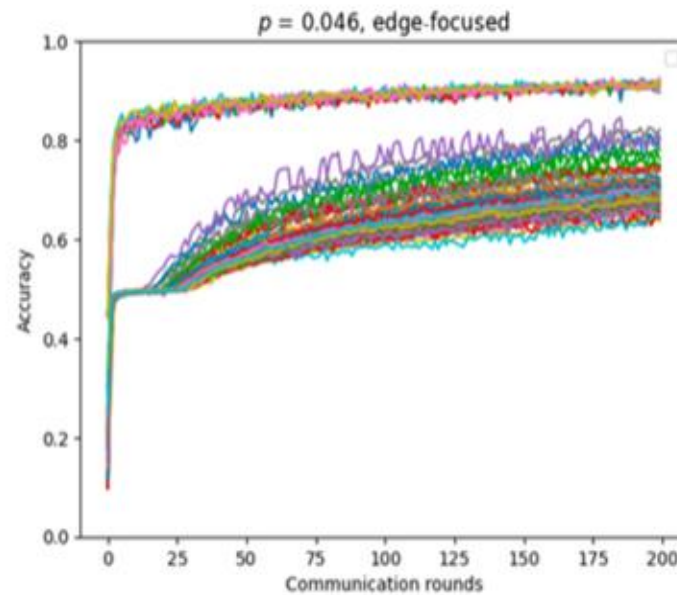
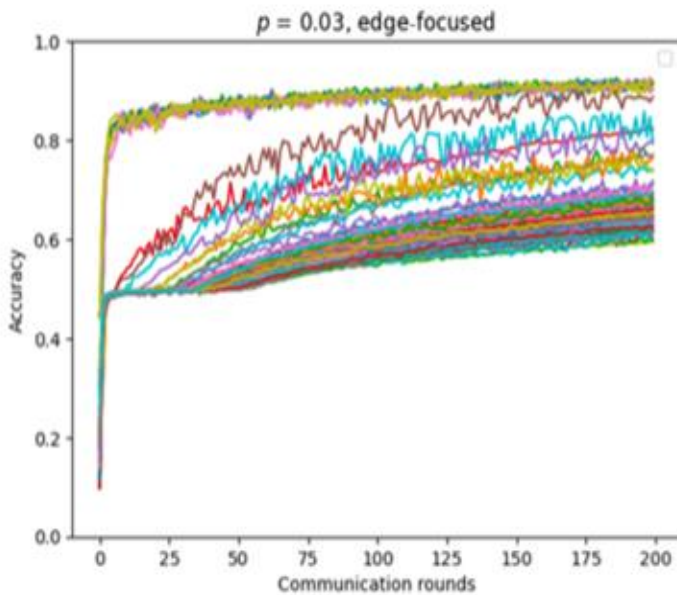
G2


  - **All nodes** receive an **equal share** (selected randomly) of data from **G1**.
  - Data from **G2** are **allocated only to the 10% highest-degree** vs **lowest-degree** nodes
- **Three topologies** were considered (all with 100 nodes):
  - Erdős–Rényi, Barabási–Albert, Stochastic block model
- Model aggregation strategy: simple **averaging**



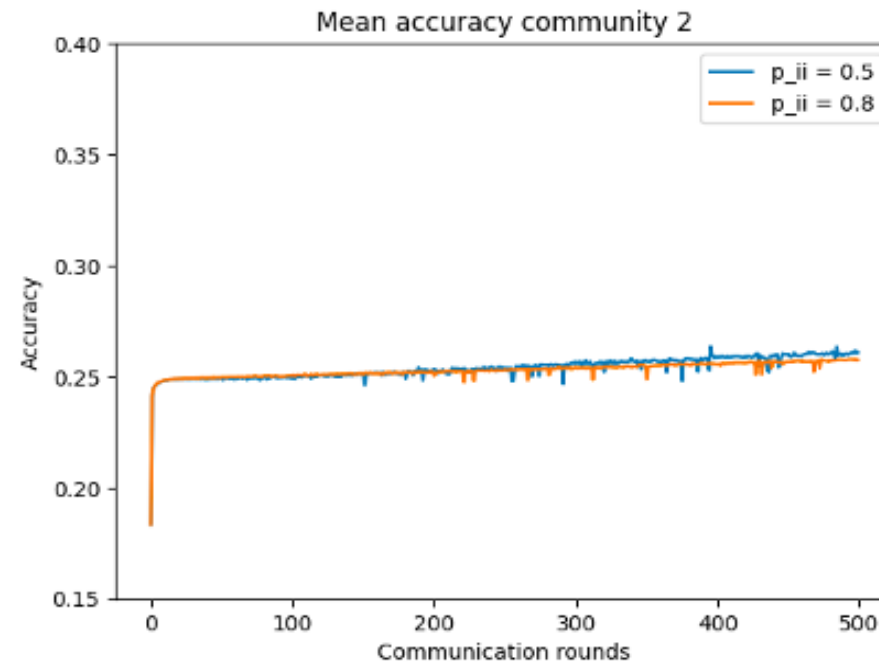
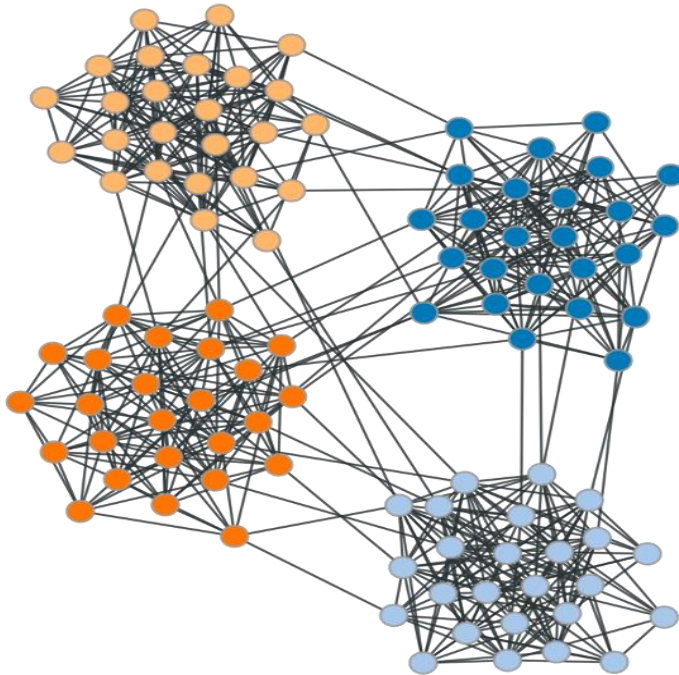
# Main results

- the **initial data distribution** on high vs low-degree nodes plays a **key role**
- when low-degree nodes have more knowledge, knowledge spreads **better** when the network is **less connected**
  - connectivity dilutes knowledge** in average-based dec learning



## Main results

- the **initial data distribution** on high vs low-degree nodes plays a **key role**
- when users are grouped in tightly knit communities, it is very **difficult for knowledge to circulate outside** of the community



## Selection strategy counts too

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- **Betweenness centrality** → How much the node bridges together distant part of the network
- **Degree centrality** → How much connections does the node have
- **Clustering coefficient** → How much the node is influential within its neighbors

A blue starburst graphic with multiple points, pointing towards the left.

Global

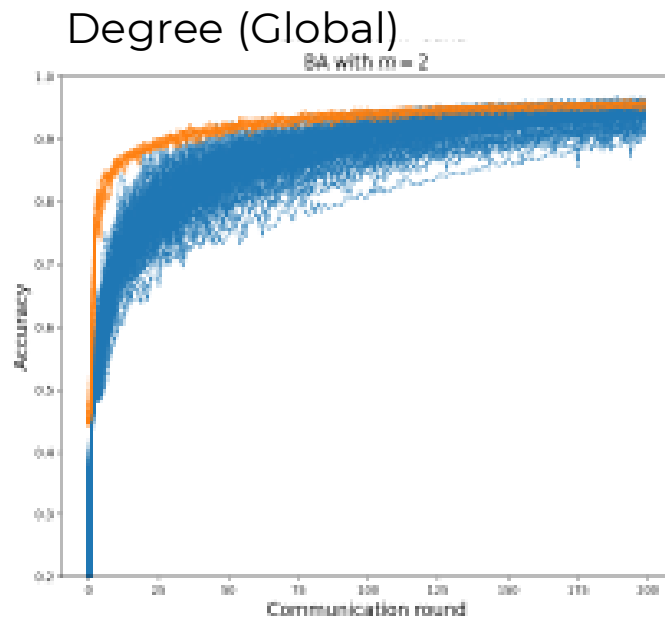
A yellow starburst graphic with multiple points, pointing towards the left.

Local

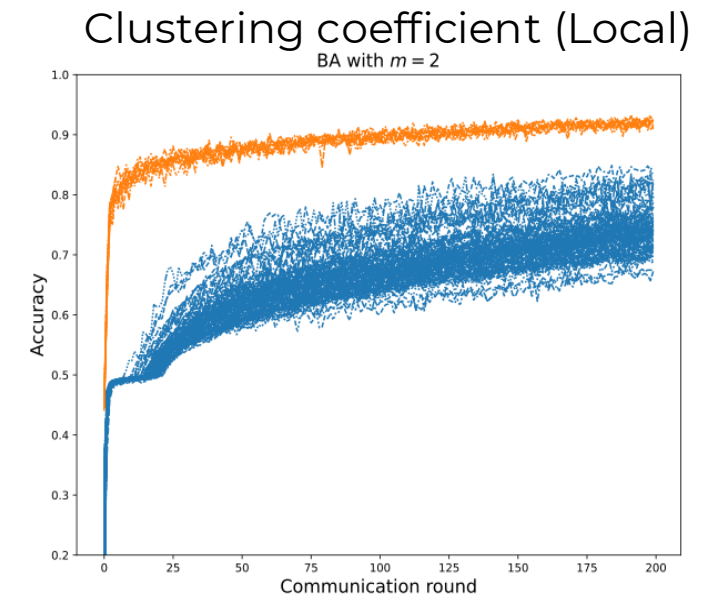
# Selection metric counts too

Information flows better when more data is given to nodes that are **globally** more influential.

Highest-focus



VS



Orange curves: nodes with more data

Blue curves: all the other nodes in the network

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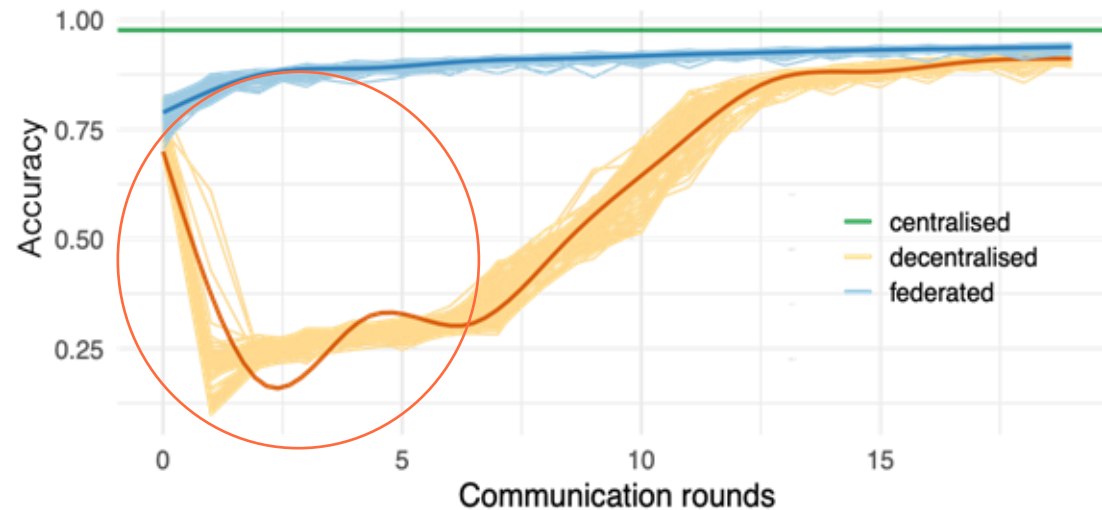
## Research direction #2:

# Enhancing local AI models through decentralized collaboration





# Aggregation is not easy w/o coordination



The accuracy drops instead of increasing!

Why the drop? It's the lack of coordination

- each node has a **different initialization** of the local (e.g., MLP) model
- due to the **permutation invariance of the hidden layers** of the neural network, coordinate-wise averaging can be detrimental without a common initialization
- Non-IID data worsen this effect

## Our solution #1: mitigation

### Aggregate

Heterogeneity-aware aggregation function (**DecDiff**)  
**Intuition:** give less importance to models that are very different from yours

### Train

Boost the learning with a **virtual teacher**  
**Intuition:** introduces a regularization element

# Aggregation strategy: beyond Decentralised Federated Average

Aggregate

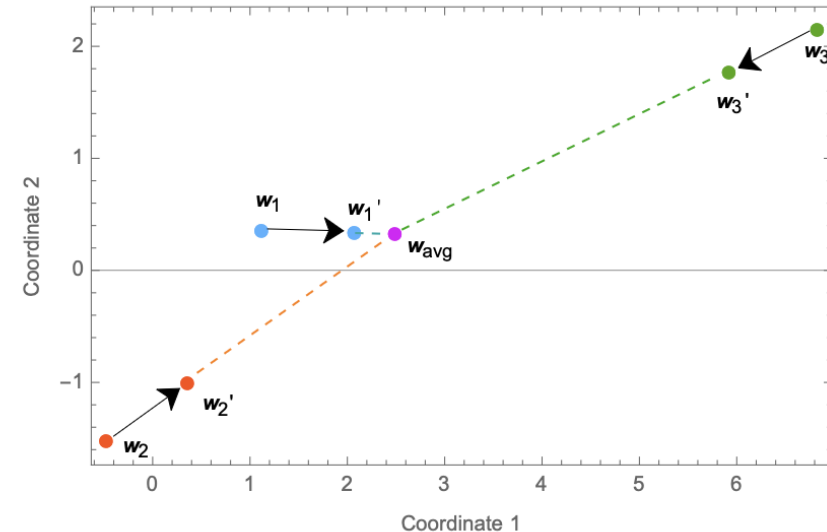
- DecDiff

$$\mathbf{w}_i^{(t)} = \mathbf{w}_i^{(t-1)} - \beta_{i,t} \frac{\mathbf{w}_i^{(t-1)} - \bar{\mathbf{w}}_i^{(t-1)}}{\|\mathbf{w}_i^{(t-1)} - \bar{\mathbf{w}}_i^{(t-1)}\|_2 + s}$$

where

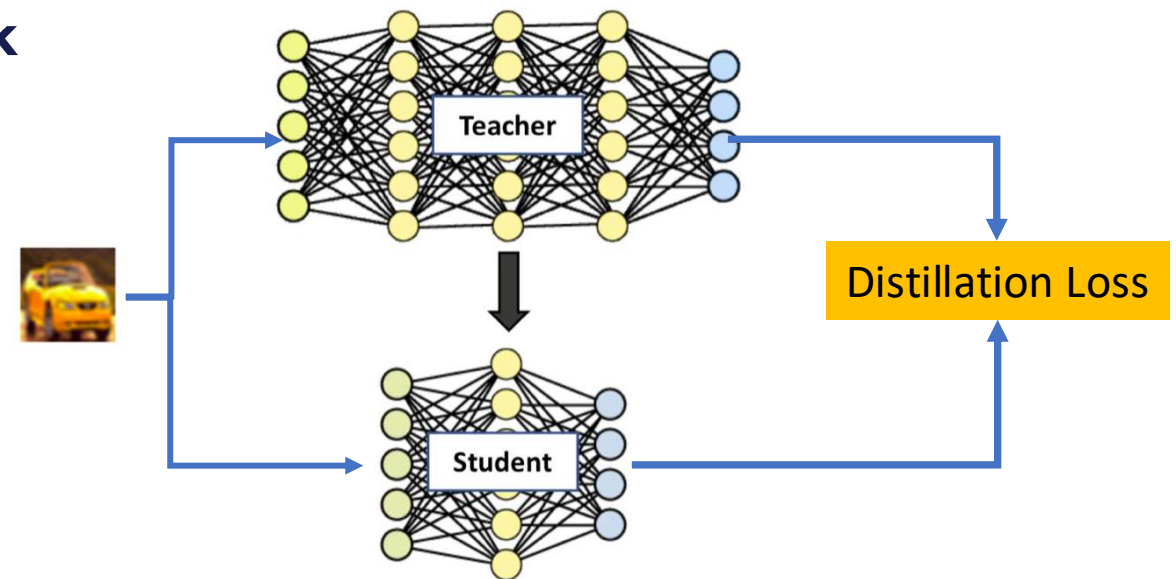
$$\bar{\mathbf{w}}_i^{(t-1)} = \frac{\sum_{j \in \mathcal{N}_i} \omega_{ij} p_{ij} \mathbf{w}_j^{(t-1)}}{\sum_{j \in \mathcal{N}_i} \omega_{ij} p_{ij}}$$

Average model  
(from neighbors)



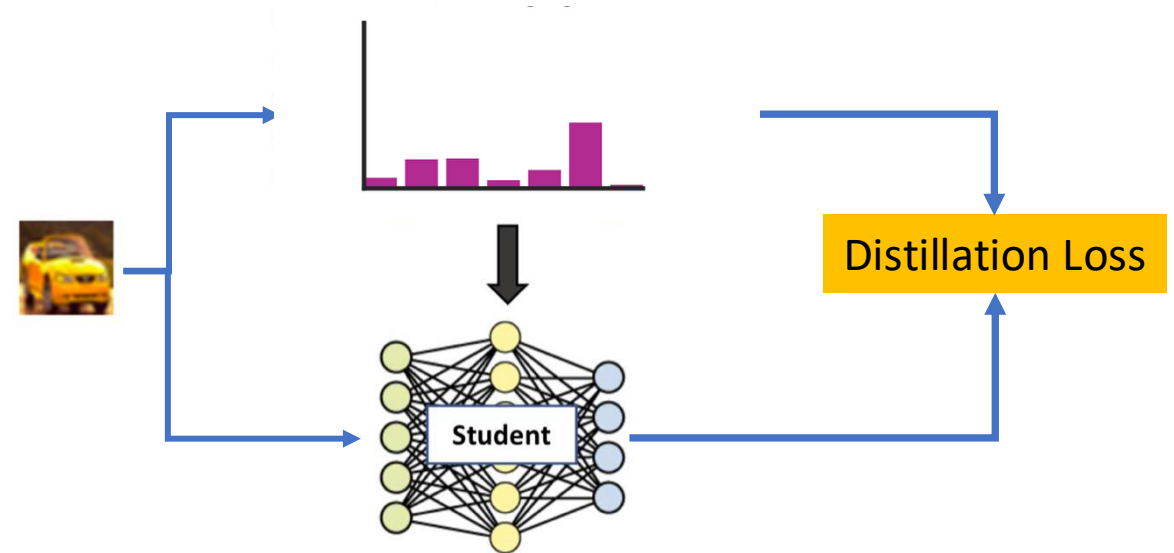
# Local training: Based on distillation

- Standard distillation
  - A **student** network tries to **mimic** a **Teacher** network
- Basic assumptions on the *Teacher* network
  - **Larger** and more capable **network**
  - Trained on **more data**



# Local training: Based on distillation

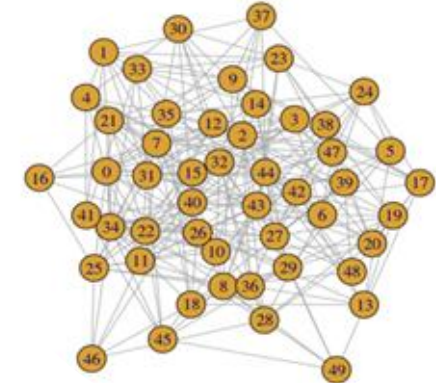
- In decentralised settings:
  - **All devices** are both **teachers** and **students**
  - Trained on local (small data)
- Potential Issues: **computational bottleneck** for devices
- Solution: **Self-distillation**
  - Replace Teacher network with a virtual teacher



# Results

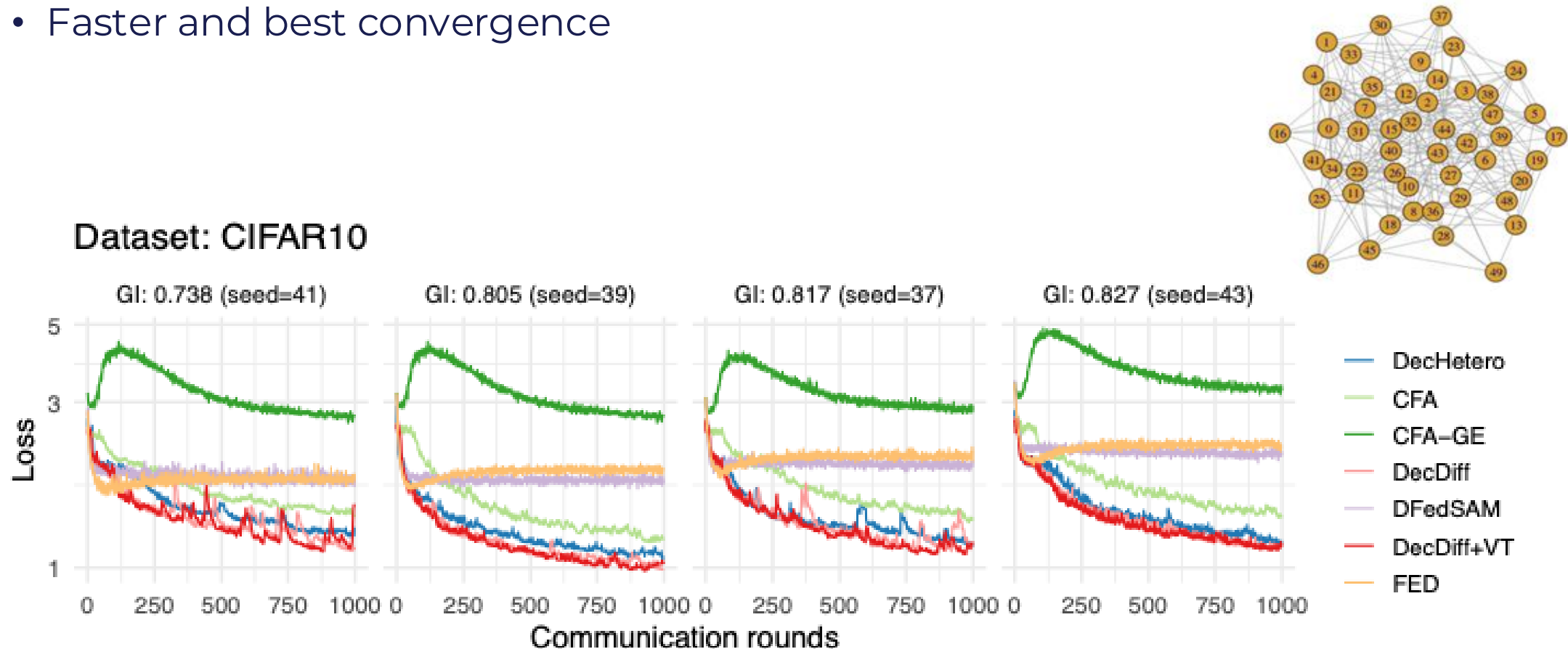
- Our DFL vs FL: close performance

Strategy	Accuracy (avg)	Conf. int.
Centralized	0.918	0
Federated	0.896	0.00204
DecDiff + Virtual Teacher	0.894	0.00206
DecDiff	0.887	0.00463
DecAvg	0.886	0.00173
SOTA benchmark #1	0.859	0.0033
SOTA benchmark #2	0.859	0.0118
No cooperation	0.769	0.0396



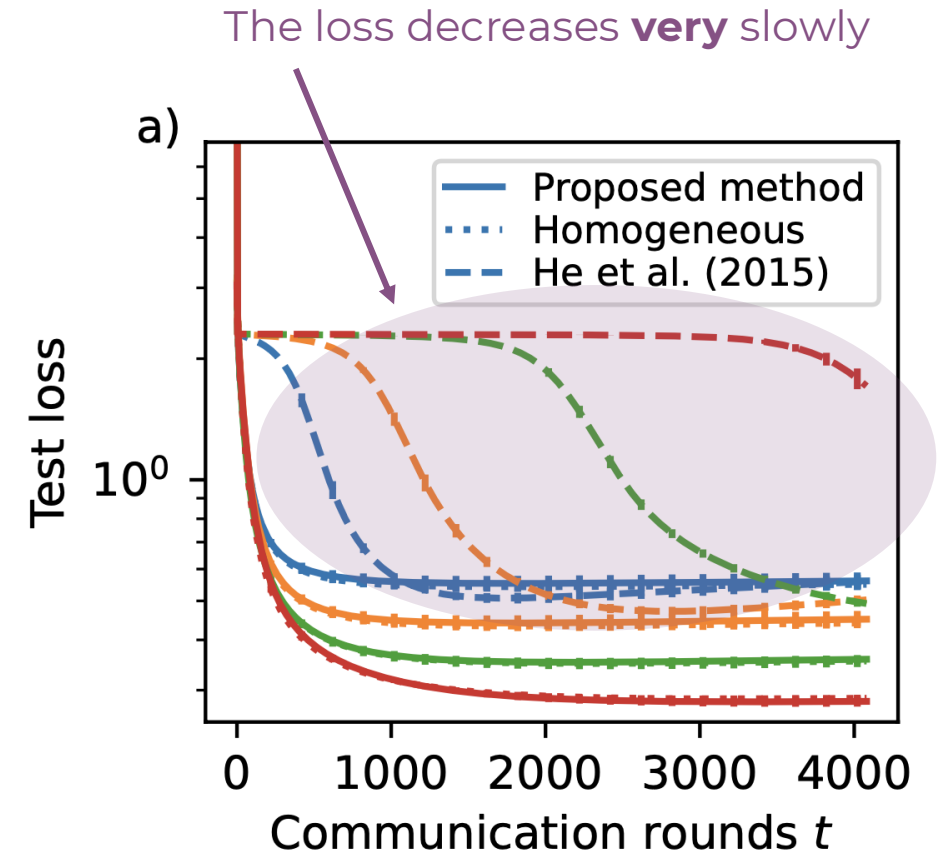
# Results

- Faster and best convergence



## Our solution #2: acceleration

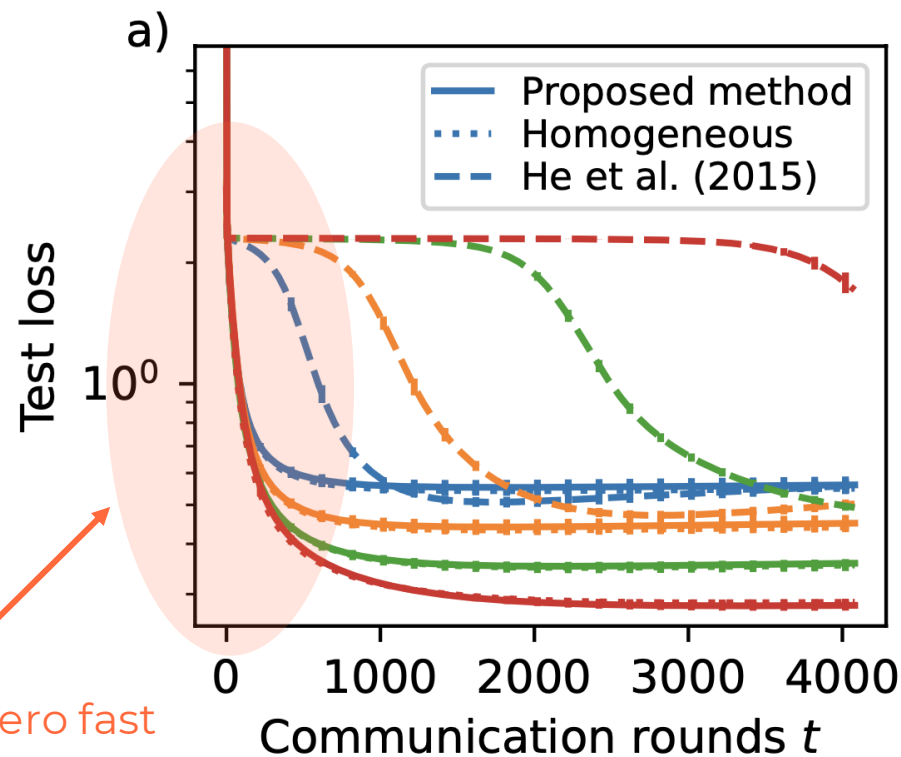
- Standard model initialization (He et al. 2015)
  - weights of layer  $l \sim \text{Gaussian}(0, \sigma_l^2)$
- In decentralized, uncoordinated settings, it results in **progressively poorer performance as the number  $n$  of nodes grows**
- We propose a novel initialization with gain correction



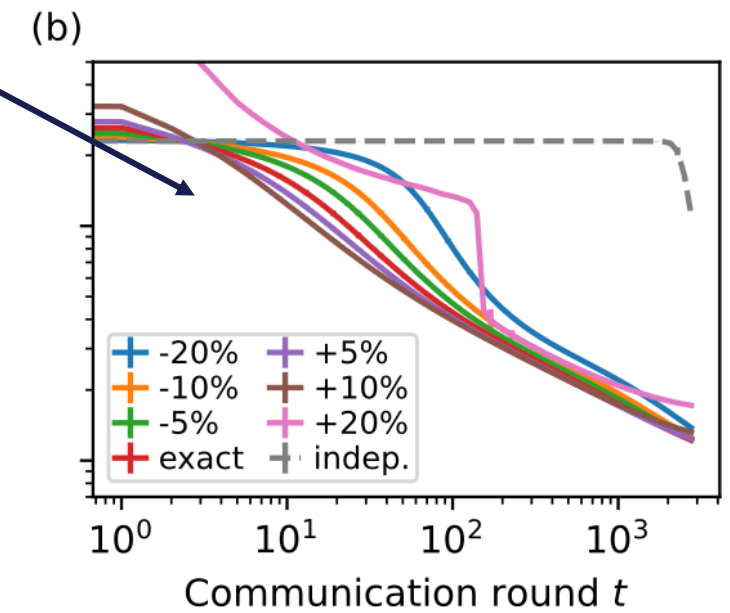


## Our solution #2: acceleration

- **HOW:** Use  $\sigma_{\text{init}} \cdot \|v_{\text{steady}}\|^{-1}$ , where  $\|v_{\text{steady}}\|$  is the  $\ell_2$ -norm of the steady-state eigenvector (corresponding to eigenvalue 1) of the Markov matrix  $A$  associated with the communication graph  $G$ , normalized to have unit sum



It works better than std init even with large estimation errors!



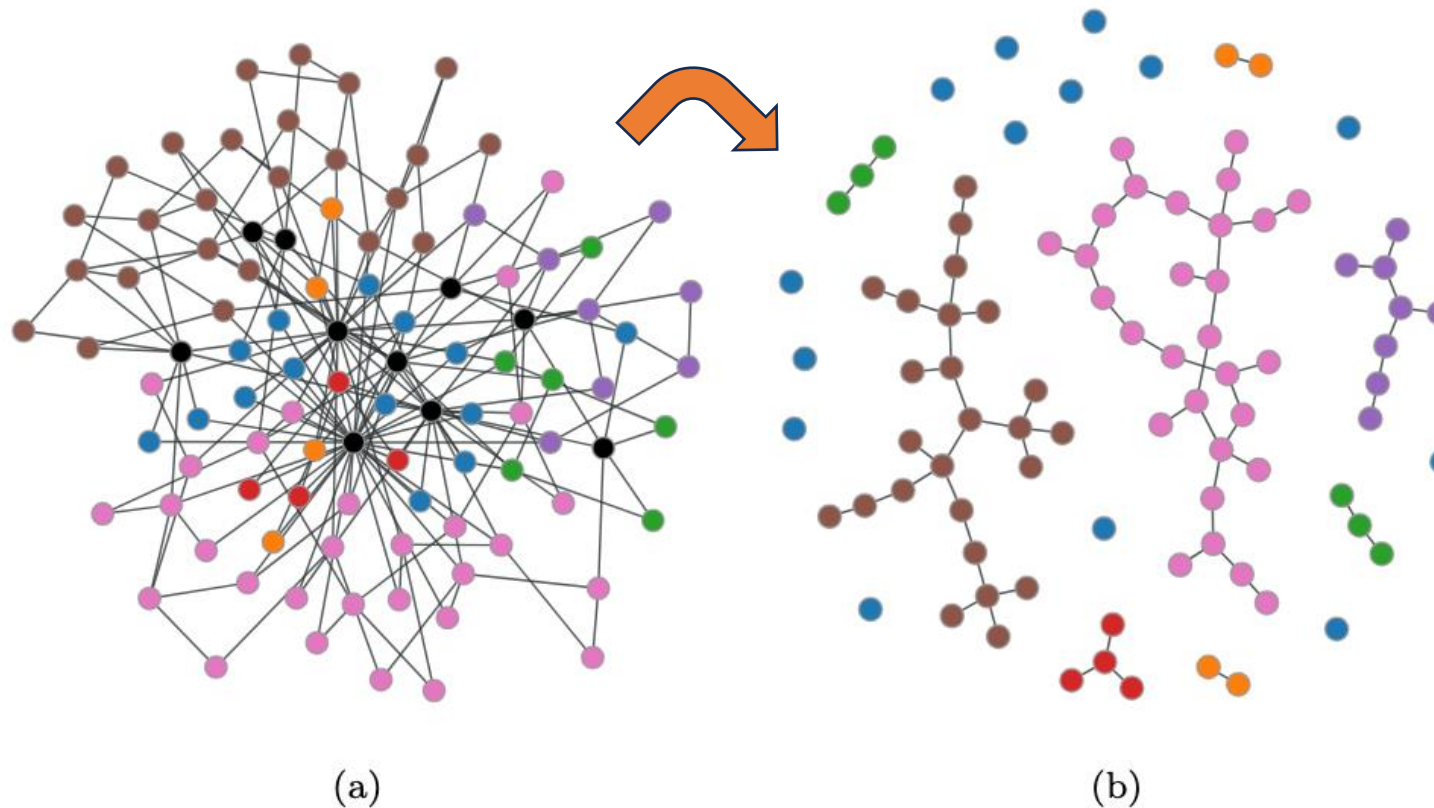
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## Research direction #4: Resilience of decentralized learning



## Resilience to data and node loss

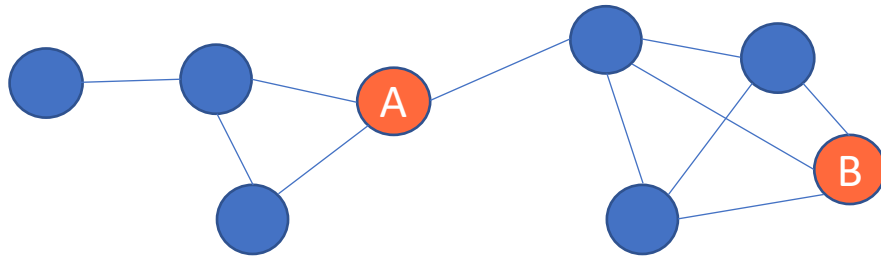
- The **most central nodes** disappear from the network
  - They have data vs they don't have data (IID vs non-IID)



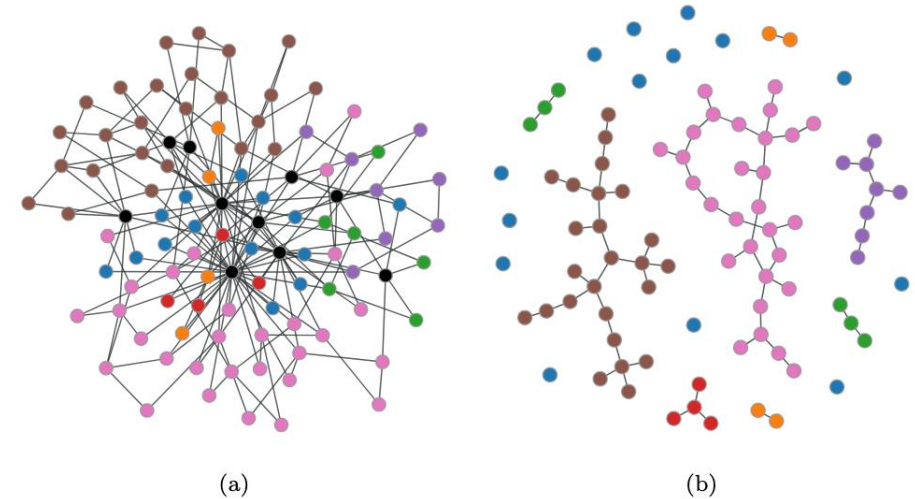
# Experimental settings: selection of cut off nodes

How do we disrupt: **switch off nodes** according to their **centrality score**

Centrality score: *Structural holes score (SH)*



We remove top 10% of nodes with highest SH



Initial

After disruption

# Disruption analysis

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## Case 1

**How:** Highly *central nodes* have no data assigned

**Central nodes role:** connectivity only

## Case 2

**How:** *central nodes* have data

**Central nodes role:** connectivity + training

Disruptions happens through time: the  $t=0$ ,  $t=2$  and  $t=10$

10% accuracy curve



50% accuracy curve



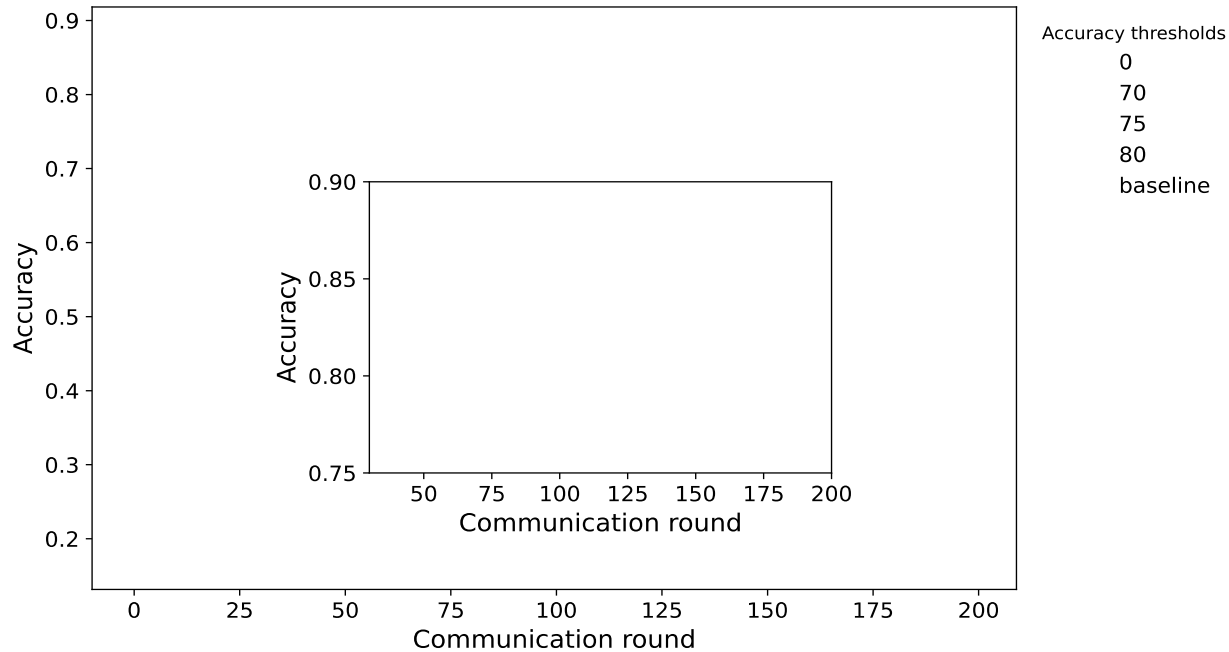
# Case 1: connectivity drops

DFL is robust  
against failures

The mean overall accuracy does not change much with  
respect to the baseline

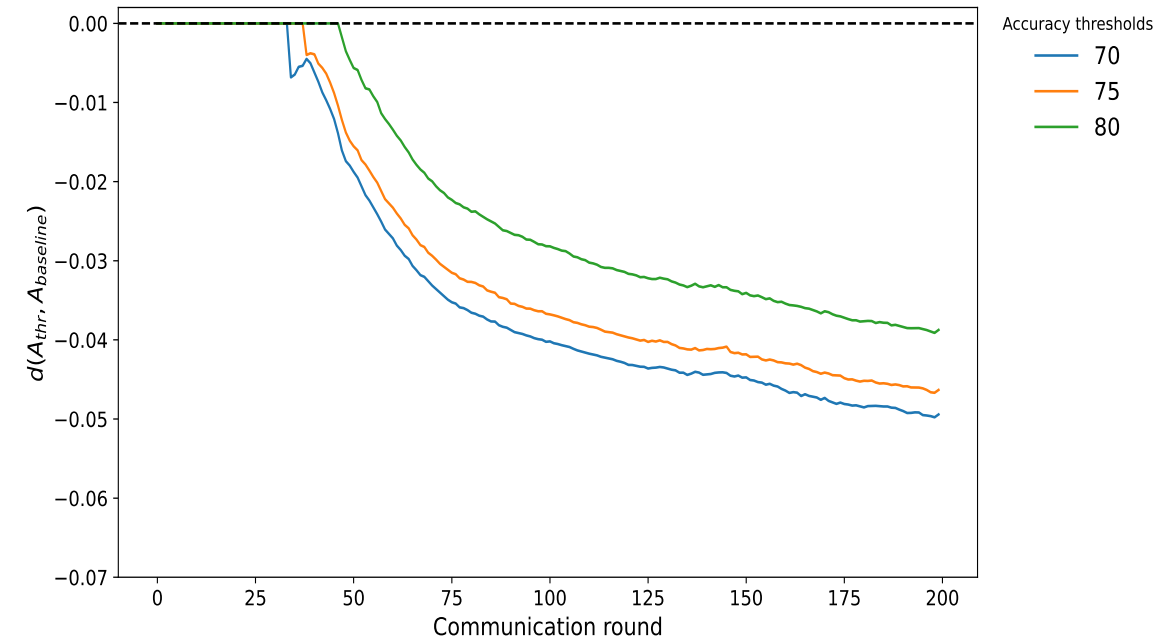
Mean accuracy

Mean accuracy over all surviving nodes  
Case 1



$$d(A_{thr}, A_{baseline}) = \frac{A_{thr}}{A_{baseline}} - 1$$

Mean accuracy difference from baseline of all surviving nodes  
Case 1

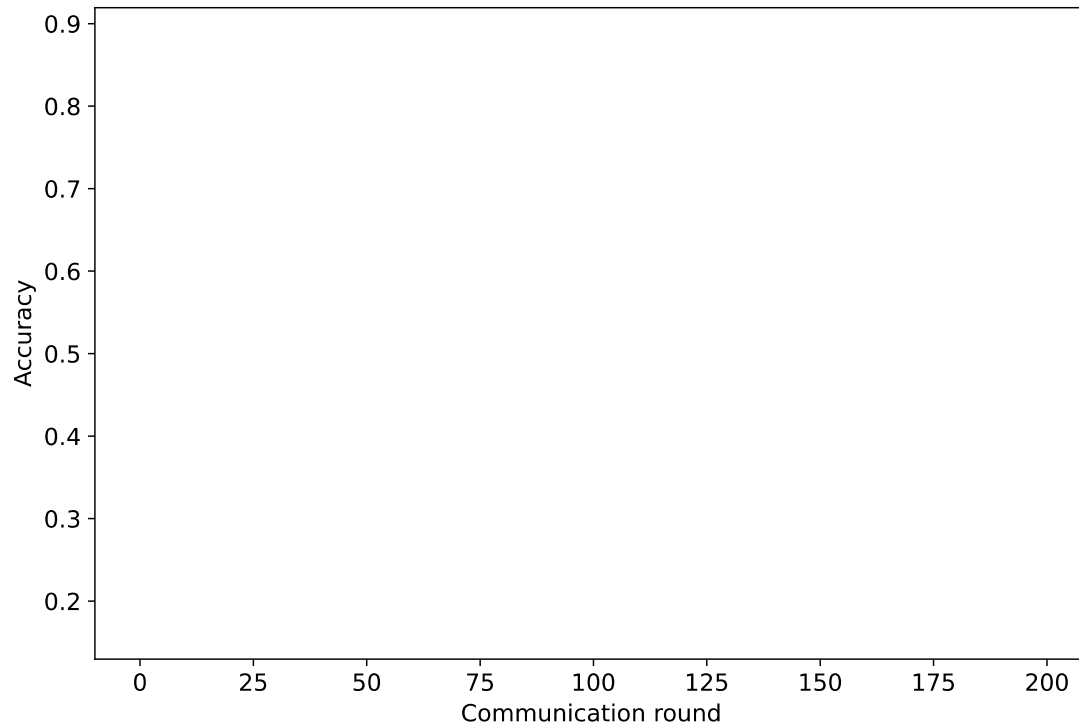


# What happens to isolated nodes? Case 1 vs Case 2

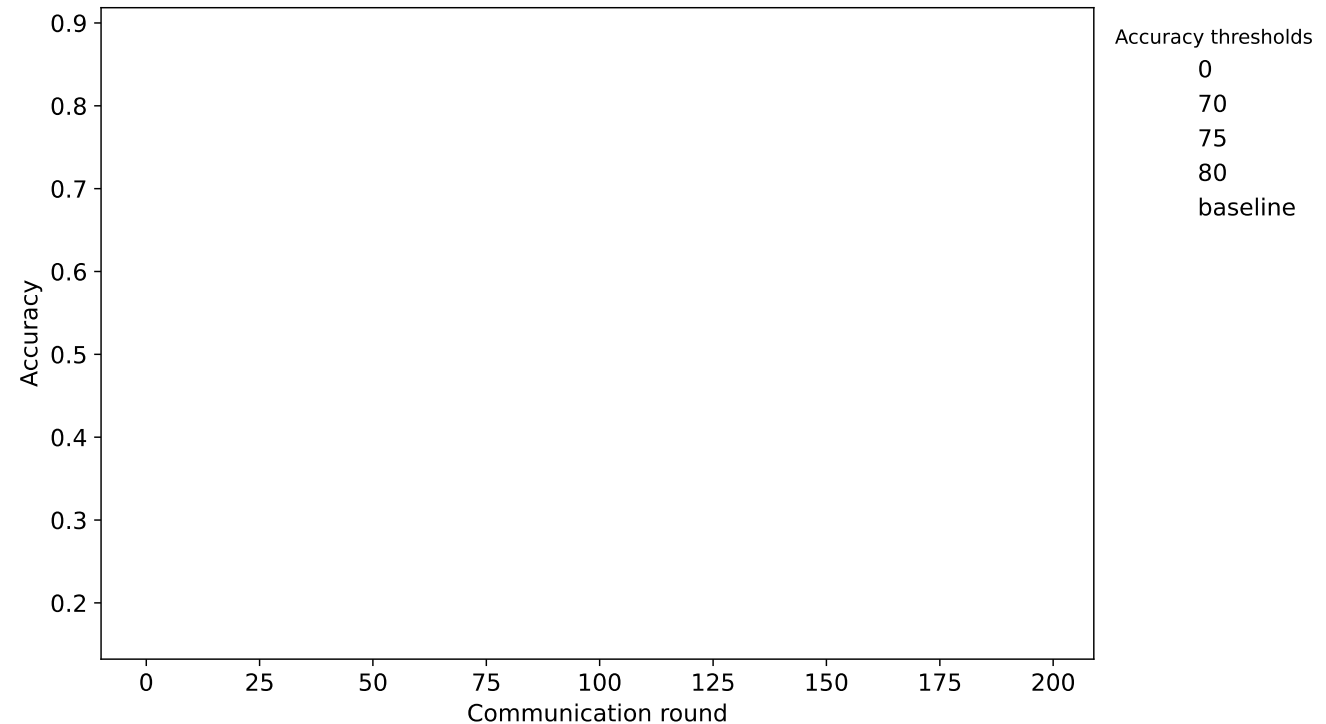
**Knowledge  
persists**

Mean accuracy of the isolated nodes is directly proportional  
to the accuracy threshold

Mean accuracy isolated nodes  
Case 1



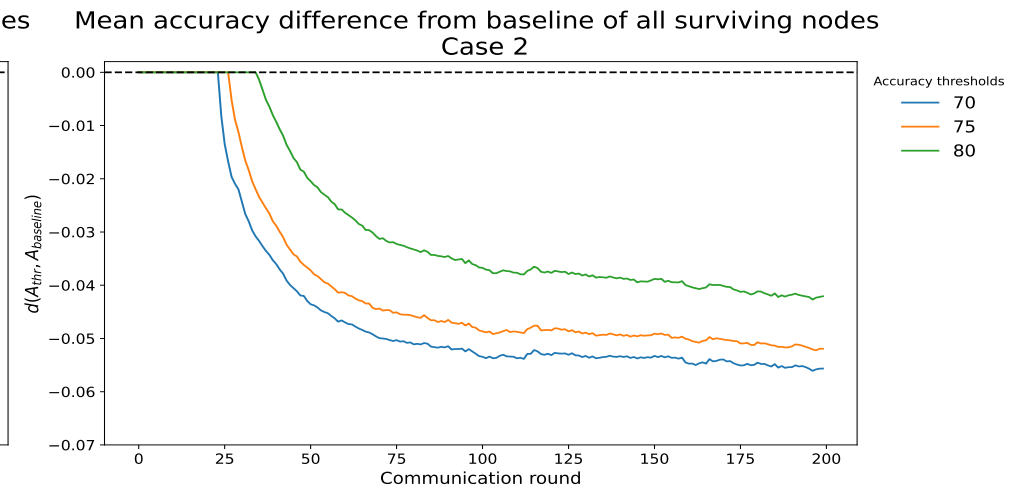
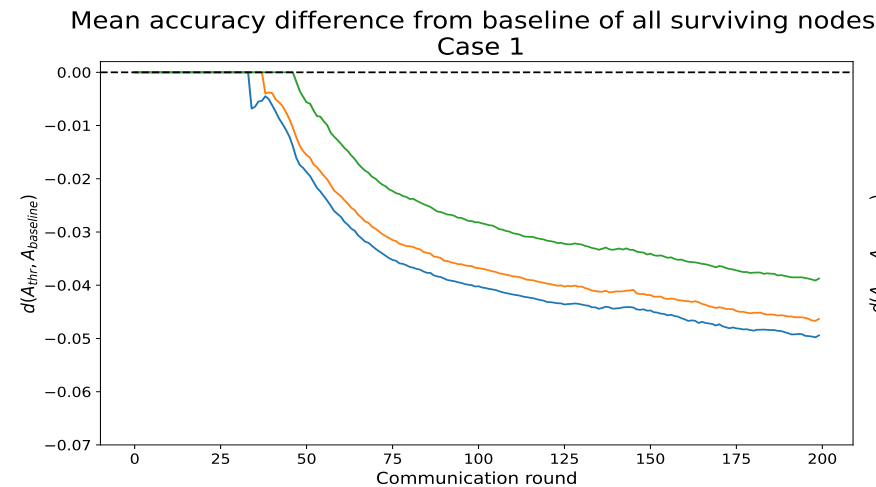
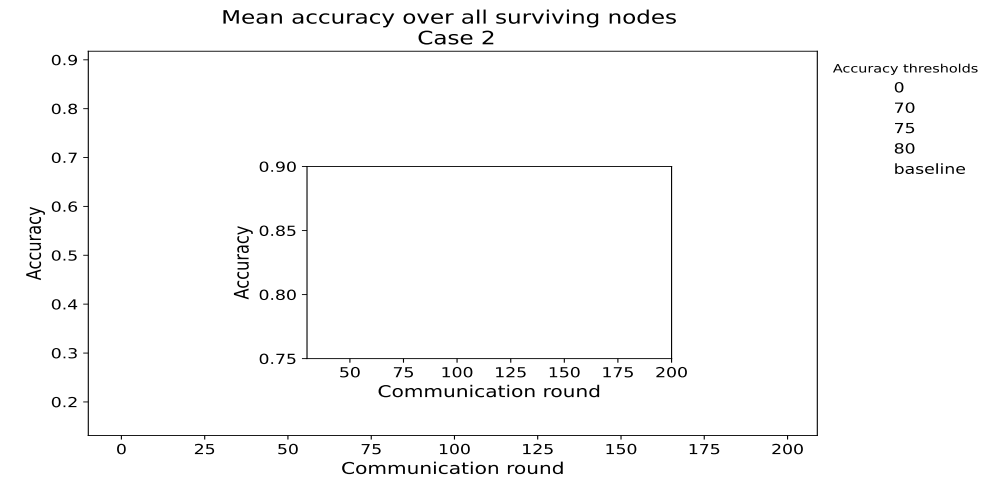
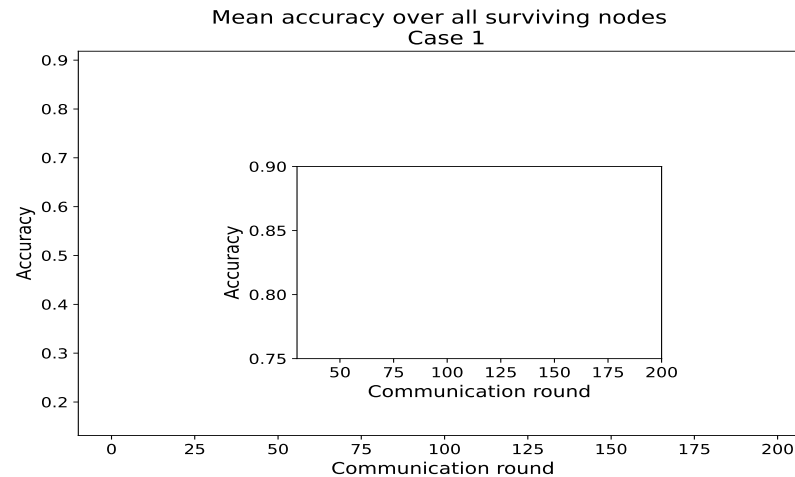
Mean accuracy isolated nodes  
Case 2



Accuracy thresholds  
0  
70  
75  
80  
baseline

The mean accuracy difference from the baseline is similar between Case 1 and Case 2

DFL can tolerate large loss of data





# Concluding

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## Key findings

- **Knowledge** acquired before disruption **persists**, and is not lost even by isolated nodes
- **Accuracy** can be recovered **if data is present “somewhere”** in the network
- Even **modest connectivity supports efficient recovery** from failures

**Decentralized learning is robust to all types of disruption**



# Resilience to low-quality data

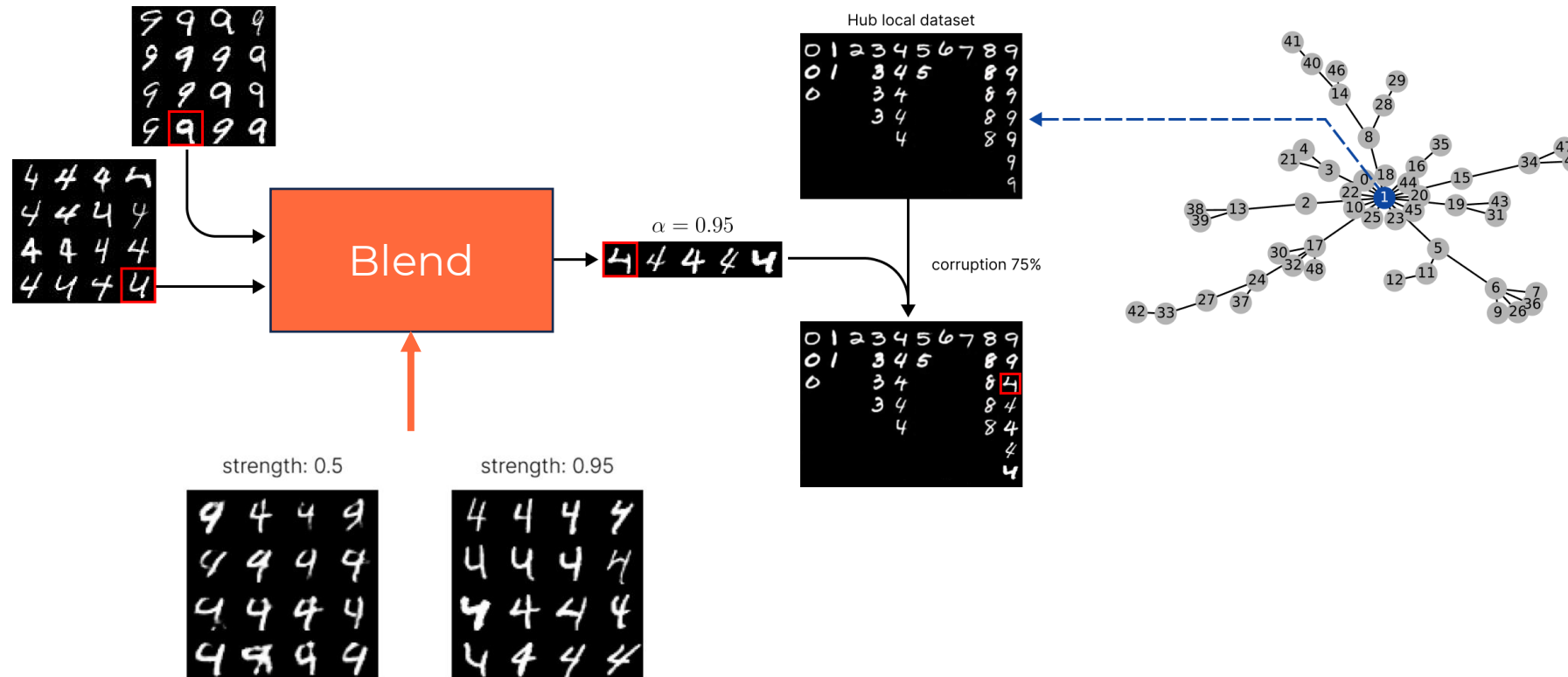
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- **RQ1:** How **sensitive** is average-based decentralized federated learning **to low-quality or corrupted data**?
- **RQ2:** To what extent is this **sensitivity influenced by the underlying network topology**?



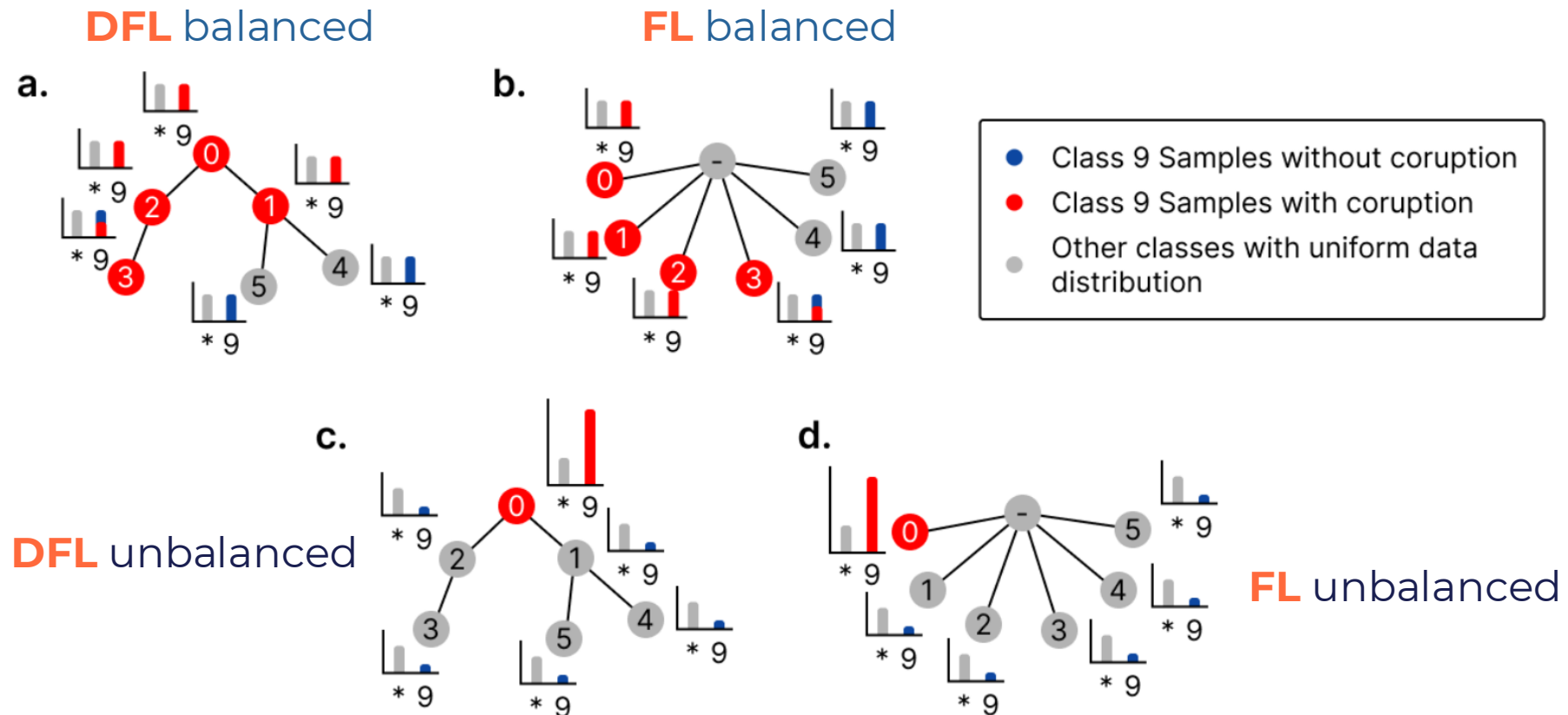
# Resilience to low-quality data

- **Low-quality data (i.e., 9s look like 4s, but labelled as 9)**

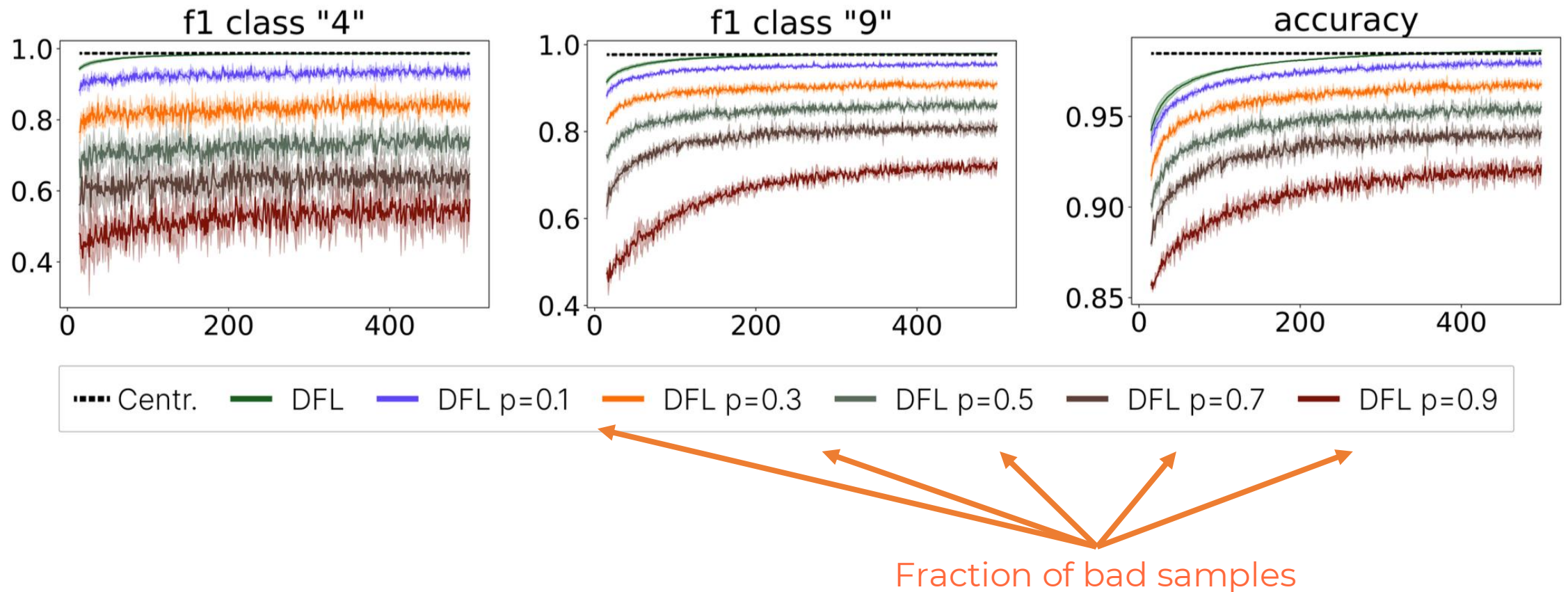


Different types of interpolation

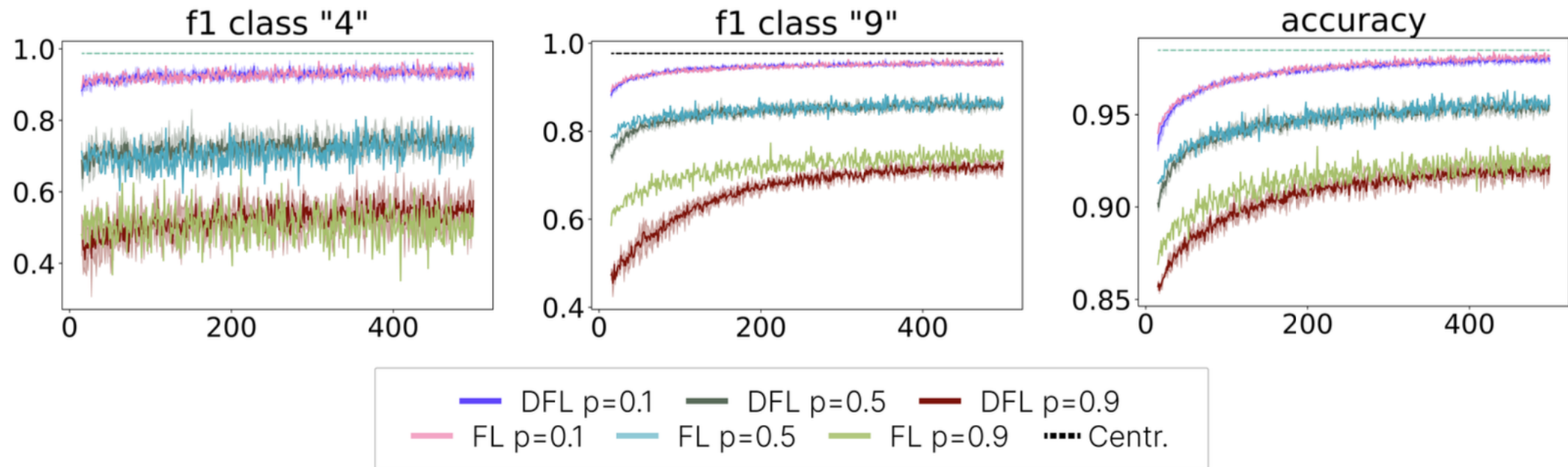
# Settings: how bad data is distributed



# Impact of corruption: Centralized VS DFL

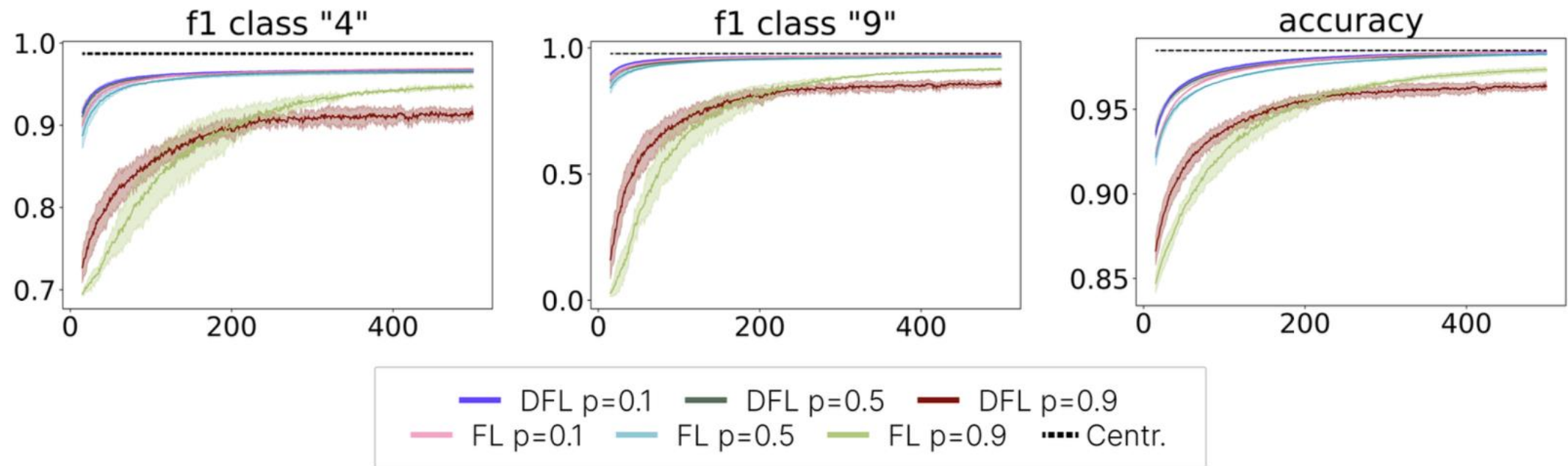


## Impact of corruption: **Balanced** corruption – DFL vs FL



No difference!

## Impact of corruption: **Unbalanced** corruption – DFL vs FL



FL less susceptible

Both show robustness

## To summarize

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- **Corruption can hide in accuracy**
  - overall accuracy stays fairly stable
- **Spread beats spike**
  - the same bad-data budget is **far more damaging when dispersed across many nodes**
- **Coordination helps resilience:**
  - **federated (server-based) learning** shows **better long-run robustness** to corruption than fully decentralized learning.

Again, we found that decentralized training is extremely resilient





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What's **left** & What's **next**?



## To recap...

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- We covered:
  - Impact of **network topology**
  - Cope with data and models' **heterogeneity**
  - **Resilience** to bad data/low quality data



## What's next

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- **Resource limitations**, i.e. quite crucial at the edge
  - Model reduction (pruning/quantization/...)
  - Alternative models, e.g., neuromorphic models and hardware
- Go beyond correlations and introduce **collaborative causality**



## What's next

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- **Adaptation** to continuously **changing environments**
  - Continual learning
  - Unlearning, i.e., selectively forget concepts.
- Security and privacy:
  - Go **beyond resilience** and explore over **attacks to agents** in decentralized and collaborative environment



Thank you for the attention!

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